

## Introduction

### Problem definition and Model.

*Efficient and reliable task executions on a fault-prone machine, under worst-case occurrence of crashes, and dynamic task arrivals of different computation times (costs)*

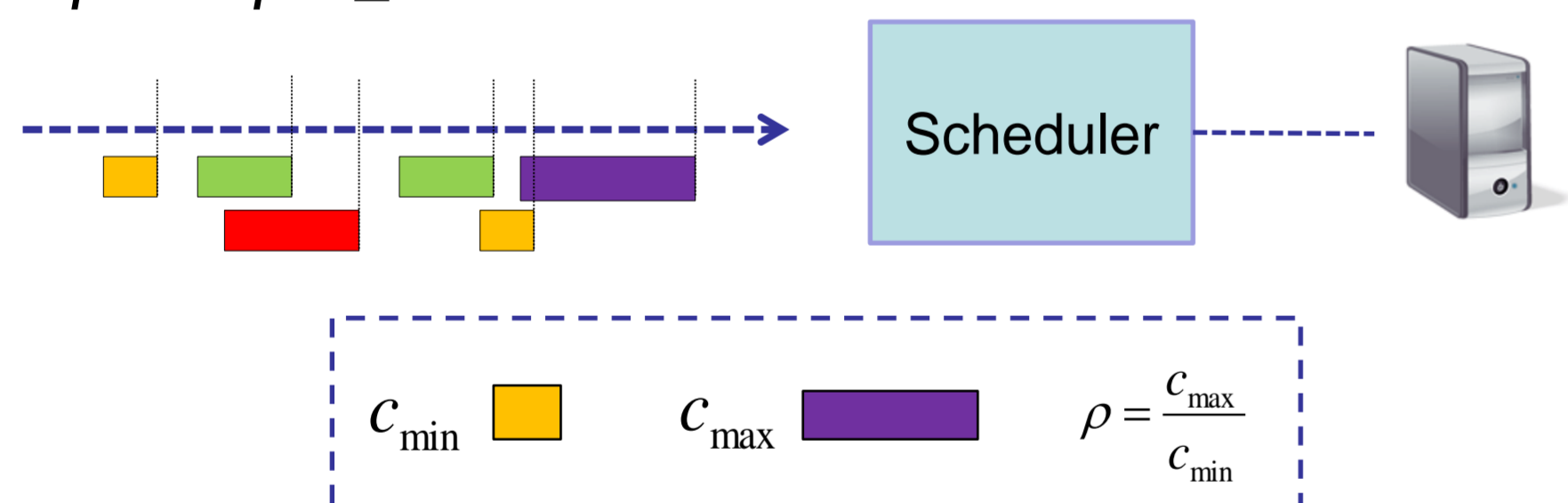
We perform *competitive analysis* of online scheduling algorithms under adversarial crash and arrival patterns [1,3]

Evaluation of 4 popular scheduling algorithms:

- Longest In System (LIS)
- Shortest In System (SIS)
- Largest Processing Time (LPT)
- Shortest Processing Time (SPT)

Introduce *speed augmentation* [1,2]

- speedup  $s \geq 1$



### Efficiency measures. Asymptotic competitiveness

#### Machine Utilization

$$\text{Completed Cost } \mathcal{C}^s(ALG, A, E) = \inf_{A \in \mathcal{A}, E \in \mathcal{E}, X \in \mathcal{X}} \lim_{t \rightarrow \infty} \frac{C_t^s(ALG, A, E)}{C_t^1(X, A, E)}$$

#### Buffering

$$\text{Pending Cost } \mathcal{P}^s(ALG, A, E) = \sup_{A \in \mathcal{A}, E \in \mathcal{E}, X \in \mathcal{X}} \lim_{t \rightarrow \infty} \frac{P_t^s(ALG, A, E)}{P_t^1(X, A, E)}$$

#### Fairness

$$\text{Latency } \mathcal{L}^s(ALG, A, E) = \inf_{A \in \mathcal{A}, E \in \mathcal{E}, X \in \mathcal{X}} \lim_{t \rightarrow \infty} \frac{L_t^s(ALG, A, E)}{L_t^1(X, A, E)}$$

$A$  : set of arrival patterns      $E$  : set of error patterns  
 $ALG \in \{LIS, SIS, LPT, SPT\}$       $X$  : offline optimal algorithm

## Speedup $s < \rho$

Algorithm	Completed Cost $\mathcal{C}^s(ALG, A, E)$	Pending Cost $\mathcal{P}^s(ALG, A, E)$	Latency $\mathcal{L}^s(ALG, A, E)$
LIS	0	$\infty$	$\infty$
SIS	0	$\infty$	$\infty$
LPT	0	$\infty$	$\infty$
SPT	$\left[ \frac{1}{2+\rho}, \frac{[\rho]-1}{[\rho]-1+\rho} \right]^*$	$\infty$	$\infty$

Lower bound holds for two task costs

If tasks can have ANY cost  $c \in [c_{\min}, c_{\max}]$ , and there is *no speedup* ( $s = 1$ ), **SPT** is **NOT** completed cost **competitive**

### Intuition for SPT lower bound:

- 1) Associate each task  $\tau$  completed by X, with the following tasks completed by SPT up to current time  $t$ :
  - The same task  $\tau$
  - Task  $w$  begin executed at  $t_\tau$  (time at which  $\tau$  was scheduled), if it was not interrupted by a crash.
- 2) Prove that all tasks completed by SPT are associated with some task completed by X
- 3) Prove that there are tasks of at most  $c_{\max}$  aggregate cost completed by X, not associated with tasks completed by SPT.

## Speedup $s \geq \rho$

### For all work conserving algorithms.

Speedup $s$	Completed Cost $\mathcal{C}^s(ALG, A, E)$	Pending Cost $\mathcal{P}^s(ALG, A, E)$
$s \geq \rho$	$[1/\rho, s]$	$[1, \rho]$
$s \geq 1 + \rho$	$[1, s]$	1

**Red bounds** hold **when** the **queue** of pending tasks **never** becomes **empty** after a point in time

### Intuition for $s \geq \rho$ general bounds:

We first show that for every task executed by X, ALG is also able to complete at least one task.

The results follow from the **observation** that the cost that can be completed by ALG is at least  $c_{\min}/c_{\max}$  times the cost of any task completed by X.

### More specific results for each algorithm.

**1-cost competitiveness** achieved with speedup  $s < 1 + \rho$  by all algorithms

ALG	Speedup $s$	Comp. Cost	Pend. Cost	Latency
LIS	$s \in [\rho, 1 + 1/\rho]$	$\left[ \frac{1}{\rho}, \frac{1}{2} + \frac{1}{2\rho} \right]$	$\left[ \frac{1+\rho}{2}, \rho \right]$	(0,1]
	$s \in [\max\{\rho, 1 + 1/\rho\}, 2]$	$\left[ \frac{1}{\rho}, \frac{1}{2} + \frac{c_{\min}}{2\rho} \right]$	$\left[ \frac{1}{2} + \frac{c}{2c_{\min}}, \rho \right]$	(0,1]
	$s \geq \max\{\rho, 2\}$	$[1, s]$	1	(0,1]
SIS	$s \in [\rho, 1 + 1/\rho]$	$\left[ \frac{1}{\rho}, \frac{c_{\min}}{\rho} \right]$	$\left[ \frac{c_{\min} + \rho}{1 + \rho}, \rho \right]$	$\infty$
	$s \geq 1 + 1/\rho$	$[1, s]$	1	$\infty$
LPT	$s \geq \rho$	$[1, s]$	1	$\infty$
SPT	$s \geq \rho$	$[1, s]$	1	$\infty$

**Proving that**, at every time instant that LIS completes a task, say  $w$ , there is some task  $\tau$  pending in X, for at least as long as  $w$ .

## References

- [1] Antonio Fernández Anta, Chrysis Georgiou, Dariusz R. Kowalski, and Elli Zavou. *Online parallel scheduling of non-uniform tasks: Trading failures for energy*. In FCT, pages 145-158, 2013.
- [2] Leah Epstein and Rob van Stee. *Online bin packing with resource augmentation*. Discrete Optimization, 4(34):322 - 333, 2007.
- [3] Eric Sanlaville and Gunter Schmidt. *Machine scheduling with availability constraints*. Acta Informatica, 35(9):795-811, 1998.